

1 Set Theory Review

1.1 Union and Intersection

$$A \cup B = \{x : x \in A \text{ or } x \in B\}$$

$$A \cap B = \{x : x \in A \text{ and } x \in B\}$$

1.2 Complement

$$A^C = \{x : x \notin A\}$$

1.3 Disjoint Sets

Two sets A_i and A_j are disjoint if

$$A_i \cap A_j = \emptyset \quad \forall i, j \neq i$$

1.4 Collectively Exhaustive Sets

Sets A_1, \dots, A_n are collectively exhaustive if

$$\bigcup_{i=1}^n A_i = S$$

1.5 Partition

Sets A_1, \dots, A_n are called a partition of S if A_1, \dots, A_n are disjoint and collectively exhaustive.

1.6 Properties of Sets

1.6.1 Commutative

$$A \cap B = B \cap A \quad A \cup B = B \cup A$$

1.6.2 Associative

$$A \cup (B \cup C) = (A \cup B) \cup C$$

$$A \cap (B \cap C) = (A \cap B) \cap C$$

1.6.3 Distributive

$$A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$

$$A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$

1.7 Relative Complement/Difference

$$A - B = \{x : x \in A \text{ and } x \notin B\}$$

$$A - B = A \cap B^C$$

1.7.1 DeMorgan's

$$(A \cup B)^C = A^C \cap B^C \quad (A \cap B)^C = A^C \cup B^C$$

2 Probability Theory Introduction

2.1 Relative Frequency

Suppose that an experiment is repeated n times under identical conditions. Let $N_0(n), N_1(n), \dots, N_k(n)$ be the number of times the outcome k happens. Then the relative frequency of outcome k is

$$f_k(n) = \frac{N_k(n)}{n} \quad \text{where } \lim_{n \rightarrow \infty} f_k(n) = p_k$$

2.2 Axioms of Probability

$$P(A) \geq 0$$

$$P(S) = 1$$

$$A \cap B = \emptyset \implies P(A \cup B) = P(A) + P(B)$$

$$P\left(\bigcup_{k=1}^{\infty} A_k\right) = \sum_{k=1}^{\infty} P[A_k]$$

If A_1, A_2 is a sequence of events s.t. $A_i \cap A_j = \emptyset \quad i \neq j$

3 Counting Methods and Sampling

Permutations of n distinct objects (k -tuples):	$n!$
Number of ordered samples with size k with replacement:	n^k
Number of ordered samples with size k without replacement:	$\frac{n!}{(n-k)!}$
Number of unordered samples with size k without replacement:	$\binom{n}{k} \frac{n!}{k!(n-k)!}$
Number of unordered samples with size k and with replacement:	$\binom{n+k}{k} = \binom{n-1+k}{n-1} = \binom{n-1+k}{k}$

3.1 Binomial Coefficient

$$\binom{n}{k} = \frac{n!}{k!(n-k)!} \quad \binom{n}{k} = \binom{n}{n-k}$$

4 Conditional Probability
If A and B are related, then the conditional probability of A given that B (and $P[B] > 0$) has occurred is

$$P[A|B] = \frac{P[A \cap B]}{P[B]}$$

5 Theorem of Total Probability

For B_1, B_2, \dots, B_n mutually exclusive events whose union equals the sample space S (e.g. B_1, \dots, B_n is a partition of S), then

$$P[A] = P[A|B_1]P[B_1] + \dots + P[A|B_n]P[B_n]$$

6 Bayes Rule

For B_1, B_2, \dots, B_n a partition of sample space S ,

$$P[B_j|A] = \frac{P[A \cap B_j]}{P[A]} = \frac{P[A|B_j]P[B_j]}{\sum_{k=1}^n P[A|B_k]P[B_k]}$$

7 Independence

If knowledge of the occurrence of event B does not alter the probability of event A , then event A is independent of B .

$$P[A] = P[A|B] = \frac{P[A \cap B]}{P[B]}$$

Define A, B to be independent if

$$P[A \cap B] = P[A]P[B]$$

Then

$$P[A|B] = P[A|B] = P[B|B] = P[B]$$

$$P[A \cap B] = P[A|B]P[B]$$

7.1 Notes on Independence

If two events have nonzero probability ($P[A] > 0, P[B] > 0$), and are mutually exclusive, then they cannot be independent.

7.2 Triplet Independence

For three events A, B, C to be independent,

- A, B, C Pairwise Independent
- knowledge of occurrence of any two events (e.g. A, B) should not effect the prob of the third (C)

7.2.1 Pairwise Independence

$$P[A \cap B] = P[A]P[B] \quad P[A \cap C] = P[A]P[C]$$

$$P[B \cap C] = P[B]P[C]$$

7.2.2 Independence of Events

$$P[C|A \cap B] = \frac{P[A \cap B \cap C]}{P[A \cap B]} = P[C]$$

Finally, for Triplet Independence, we must have

$$P[A \cap B \cap C] = P[A]P[B]P[C]$$

8 Sequential Experiments

8.1 Bernoulli Trials

Let k be the num of successes in n independent Bernoulli trials. Then the probabilities of k are given by binomial probability law

$$p_n(k) = \binom{n}{k} p^k (1-p)^{n-k} \quad \text{for } k = 0, \dots, n$$

8.2 Multinomial Probability Law

Let B_1, B_2, \dots, B_M be a partition of the sample space S , and let $P[B_j] = p_j$. Also, the events are disjoint:

$$p_1 + p_2 + \dots + p_M = 1$$

The multinomial probability law is

$$P[(k_1, \dots, k_M)] = \frac{n!}{k_1! \dots k_M!} p_1^{k_1} \dots p_M^{k_M}$$

8.3 Geometric Probability Law

The probability that more than K trials are required before a success (with probability $p, q = 1 - p$) occurs in a series of repeated independent Bernoulli trials is

$$P[m > K] = p \sum_{m=K+1}^{\infty} q^{m-1} = pq^K \frac{1}{1-q} = q^K$$

The probability that K trials are required for a success (with probability $p, q = 1 - p$) is

$$P[m = K] = (p)(1-p)^{K-1} = pq(K-1)$$

8.3.1 Hypergeometric Distribution

$$P(X = k) = \frac{\binom{K}{k} \binom{N-K}{n-k}}{\binom{N}{n}}$$

Where K is the number of success in the population, n is the number of observed successes, N is the population size, and n is the sample size.

9 Random Variables (RV)

A Random Variable X is a function that assigns a real number $X(\zeta)$ to each outcome ζ in the sample space of a random experiment.

10 Discrete Random Variable (DRV)

A Discrete Random Variable X is defined as a random variable that assumes values from a countable set.

10.1 PMF

$$p_X(x) = P[X = x] = P[\zeta : X(\zeta) = x] \quad x \in \mathbb{R}$$

$$\text{For } x_k \in S_X, \quad p_X(x_k) = P[A_k]$$

10.1.1 PMF Properties

$$p_X(x) \geq 0 \quad \forall x$$

$$\sum_{x \in S_X} p_X(x) = \sum_k p_X(x_k) = \sum_k P[A_k] = 1$$

$$P[X \in B] = \sum_{x \in B} p_X(x) \quad \text{where } B \subset S_X$$

10.2 Conditional PMF

Let X be a DRV with PMF $p_X(x)$, and $\exists C, P[C] > 0$. The Conditional PMF is given by

$$p_X(x|C) = P[X = x|C] = \frac{P[\{X = x\} \cap C]}{P[C]}$$

10.3 Expected Value

The expected value (or mean) of a DRV is

$$E[X] = \sum_{x \in S_X} x p_X(x) = \sum_k x_k p_X(x_k)$$

$$\mathbb{E}[|x|] = \sum_k |x_k| p_X(x_k) < \infty$$

10.4 Variance, Standard Deviation

The variance of a random variable X is

$$\sigma_X^2 = \text{VAR}[X] = E[(X - E[X])^2] = E[X^2] - (E[X])^2$$

The Standard Deviation is

$$\sigma_X = \text{STD}[X] = \sqrt{\text{VAR}[X]}$$

10.5 Expected Value and Variance Properties

$$E[g(X) + h(X)] = E[g(X)] + E[h(X)]$$

$$E[aX] = aE[X] \quad E[X + c] = E[X] + c$$

$$\text{VAR}(cX) = c^2 \text{VAR}(X) \quad \text{VAR}(X + c) = \text{VAR}(X)$$

10.6 Conditional Expected Value

For X a DRV, and suppose we know B has occurred,

$$m_X|B = E[X|B] = \sum_{x \in S_X} x p_X(x|B)$$

$$= \sum_k x_k p_X(x_k|B)$$

10.7 Conditional Variance

$$\text{VAR}[X|B] = E[(X - m_X|B)^2|B] =$$

$$\sum_{k=1}^{\infty} (x_k - m_X|B)^2 p_X(x_k|B) = E[X^2|B] - m_X^2|B$$

11 Cumulative Distribution Function

PMF uses events $\{X = b\}$, whereas Cumulative Distribution Functions (CDF) use events $\{X \leq b\}$.

$$F_X(x) = P[X \leq x]$$

11.1 Properties of the CDF

$$0 \leq F_X(x) \leq 1$$

$$\lim_{x \rightarrow \infty} F_X(x) = 1 \quad \lim_{x \rightarrow -\infty} F_X(x) = 0$$

$$F_X(a) \leq F_X(b) \quad \forall a < b$$

$$F_X(b) = \lim_{h \rightarrow 0} F_X(b+h) = F_X(b^+)$$

$$P[a < X \leq b] = F_X(b) - F_X(a)$$

$$P[X = b] = F_X(b) - F_X(b^-)$$

$$P[X > x] = 1 - F_X(x)$$

$$\lim_{x \rightarrow \infty} F_X(x) = 1 - F_X(x)$$

11.2 CDF of a Discrete RV

$$F_X(x) = \sum_{x_k \leq x} p_X(x_k) = \sum_k P[X(x_k)]u(x-x_k)$$

11.3 CDF of a Continuous RV

$$F_X(x) = \int_{-\infty}^x f(t)dt$$

11.4 Conditional CDF

$$F_X(x|C) = \frac{P[\{X \leq x\} \cap C]}{P[C]} \quad \text{if } P[C] > 0$$

12 Probability Density Function

$$f_X(x) = \frac{d}{dx} F_X(x)$$

12.1 Properties of the PDF

$$f_X(x) \geq 0 \quad \int_{-\infty}^{\infty} f_X(x)dx = 1$$

$$P[a \leq X \leq b] = \int_a^b f_X(x)dx$$

$$F_X(x) = \int_{-\infty}^x f_X(t)dt$$

12.2 PDF of a Discrete RV

$$u(x) = \int_{-\infty}^x \delta(t)dt$$

$$f_X(x) = \frac{d}{dx} F_X(x) = \sum_k p_X(x_k) \delta(x-x_k)$$

12.3 Conditional PDF

$$f_X(x|C) = \frac{d}{dx} F_X(x|C)$$

12.4 Application of Theorem of Total Probability

Suppose events B_1, B_2, \dots, B_n partition the sample space S .

$$F_X(x) = \sum_{i=1}^n P[X \leq x|B_i]P[B_i]$$

$$= \sum_{i=1}^n F_X(x|B_i)P[B_i]$$

$$f_X(x) = \frac{d}{dx} F_X(x) = \sum_{i=1}^n f_X(x|B_i)P[B_i]$$

13 Gaussian (Normal) RV

The PDF for the Gaussian Random Variable is given in the table.

13.1 Gaussian CDF

ϕ is the CDF for a standard Gaussian.

$$\phi(z) = \frac{1}{\sqrt{2\pi}} e^{-z^2/2}$$

$$\phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-t^2/2} dt$$

$$Q(z) = 1 - \phi(z) = P[X > z]$$

$$Q(0) = 1/2 \quad Q(-x) = 1 - Q(x)$$

13.3 Standard Gaussian RV

To move from any Gaussian to Standard (i.e. $X \sim N(m, \sigma^2) \rightarrow Z \sim N(0, 1)$), use

$$z = \frac{x - m}{\sigma}$$

14 Other Features of CRV's

14.1 Expected Value

$$E[X] = \int_{-\infty}^{+\infty} tf_X(t)dt$$

$$F_X(x) = F_X(x|C)$$

$$G_N(z) = E[z^N] = \int_{-\infty}^{\infty} t^N f_X(t)dt$$

$$G_N(j\omega) = \int_{-\infty}^{\infty} e^{j\omega t} f_X(t)dt$$

$$G_N(j\omega) = \phi_N(\omega)$$

14.2 PMF Relationship

$$\text{PMF: } p_N(k) = \frac{1}{k!} \frac{d^k}{dz^k} G_N(z)|_{z=0}$$

14.3 Laplace Transform of PDF

$$X(s) = \int_0^{\infty} f_X(x)e^{-sx} dx = E[e^{-sX}]$$

14.1.1 Expected Value of $Y=g(X)$

$$E[Y] = \int_{-\infty}^{\infty} g(x)f_X(x)dx$$

14.1.2 Conditional Expected Value

$$E[X|A] = \int_{-\infty}^{\infty} xf_X(x|A)dx$$

14.2 Variance, Standard Deviation

The variance of a random variable X is

$$\text{VAR}[X] = E[(X - E[X])^2] = E[X^2] - (E[X])^2$$

The standard deviation is

$$E[X+Y] = E[X] + E[Y]$$

27.1 Expected Value and Independence

Let $g(X, Y) = g_1(X)g_2(Y)$, and X, Y independent

$$Z = XY \leftrightarrow E[Z] = E[XY] = E[X]E[Y]$$

$$E[g(X, Y)] = E[g_1(X)]E[g_2(Y)]$$

28. Joint Moment

If X, Y discrete:

$$E[X^j Y^k] = \sum_i \sum_n x_i^j y_n^k p_{XY}(x_i, y_n)$$

If X, Y jointly continuous:

$$E[X] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x^j y^k f_{XY}(x, y) dx dy$$

28.1 Correlation

$$E[XY] = E[X^{j=1} Y^{k=1}]$$

If $E[XY] = 0$, then X, Y are orthogonal.

28.2 Central Moment

$$E[(X - E[X])^j \cdot (Y - E[Y])^k]$$

28.2.1 Variance

$$\text{VAR}(X) = E[(X - E[X])^2 \cdot (Y - E[Y])^0]$$

29 Covariance

$$\text{COV}(X, Y) = E[(X - E[X])(Y - E[Y])]$$

$$= E[(X - E[X])^1 \cdot (Y - E[Y])^1] = E[XY] - E[X]E[Y]$$

If $E[X] = 0$ and/or $E[Y] = 0$, then

$$\text{COV}(X, Y) = E[XY]$$

29.1 Correlation Coefficient

$$\rho_{XY} = \frac{\text{COV}(X, Y)}{\sigma_X \sigma_Y}, \quad -1 \leq \rho_{XY} \leq 1$$

If X, Y uncorrelated, then

$$\text{COV}(X, Y) = 0, \quad E[XY] = E[X]E[Y], \quad \rho_{XY} = 0$$

If X, Y independent, then they are uncorrelated.

29.2 Covariance Properties

$$\text{COV}(X, X) = \text{VAR}(X) \quad \text{COV}(X, Y) = \text{COV}(Y, X)$$

$$\text{COV}(\alpha X, Y) = \alpha \text{COV}(X, Y)$$

$$\text{COV}(X + c, Y) = \text{COV}(X, Y)$$

$$\text{COV}(X + Y, Z) = \text{COV}(X, Z) + \text{COV}(Y, Z)$$

30 Conditional Probabilities

30.1 Case 1: X, Y Discrete - Conditional PMF

$$P_Y(y|x) = P[Y=y|X=x] =$$

$$= \frac{P[X=x, Y=y]}{P[X=x]} = \frac{p_{XY}(x, y)}{p_X(x)}$$

$$p_Y(y_k|x_j) = \frac{p_{XY}(x_j, y_k)}{p_X(x_j)} \rightarrow$$

$$p_{XY}(x_j, y_k) = p_Y(y_k|x_j) \cdot p_X(x_j)$$

$$P[Y \in A | X = x_k] = \sum_{y_j \in A} p_{Y|X}(y_j|x_k)$$

$$P[Y \in A] = \sum_{x_k} P[Y \in A | X = x_k] p_X(x_k)$$

30.2 Case 2: X discrete, Y continuous - Conditional PDF

$$f_{Y|X}(y|x_k) = \frac{P[Y \leq y, X = x_k]}{P[X = x_k]}, \quad P[X = x_k] > 0$$

$$f_Y(y|x_k) = \frac{d}{dy} f_{Y|X}(y|x_k)$$

If X, Y independent,

$$P[Y \in A | X = x_k] = \int_{y \in A} f_Y(y|x_k) dy$$

30.3 Case 3: X, Y continuous - Conditional PDF

$$f_{Y|X}(y|x) = \frac{d}{dy} f_Y(y|x) = \frac{f_{XY}(x, y)}{f_X(x)}$$

$$P[Y \in A | X = x] = \int_{y \in A} f_Y(y|x) dy$$

$$P[Y \in A] = \int_{-\infty}^{\infty} P[Y \in A | X = x] f_X(x) dx$$

If X, Y independent,

$$f_{Y|X}(y|x) = \frac{f_X(x)f_Y(y)}{f_X(x)} = f_Y(y)$$

30.4 Bayes Rule

$$f_{Y|X}(y|x) = \frac{f_{XY}(x, y)}{f_X(x)}$$

$$f_{XY}(x, y) = f_Y(y|x)f_X(x) = f_X(x|y)f_Y(y)$$

$$f_{Y|X}(y|x) = \frac{f_{XY}(x|y)f_Y(y)}{f_X(x)}$$

31 Conditional Expectation

31.1 X, Y Discrete

$$E[Y|x] = \sum_{y_k} p_Y(y_k|x)$$

31.2 X, Y Continuous

$$E[Y|x] = \int_{-\infty}^{\infty} y f_Y(y|x) dy$$

31.3 Law of total Expectation

Since $E[Y|x] = g(x)$, we define $E[g(x)]$

$$E[E[Y|x]] = \int_{-\infty}^{\infty} E[Y|x] f_X(x) dx = E[Y]$$

for any function $h(Y)$, where $E[h(Y)] = E[E[h(Y)|x]]$

$$E[Y^k] = E[E[Y^k|x]]$$

32 Functions of Two RVs

Let $Z = g(X, Y)$ (function of two RVs). Then,

$$f_Z(z) = P[X \in R_z] = \iint_{(x,y) \in R_z} f_{XY}(x, y) dx dy$$

$$f_Z(z) = \frac{d}{dz} F_Z(z) = \int_{-\infty}^{\infty} f_{XY}(x, z-x) dx$$

If X, Y independent, then

$$f_Z(z) = f_X(x) * f_Y(y) = \int_{-\infty}^{\infty} f_X(x) f_Y(z-x) dx$$

33 Transformations of Two RVs

Let $W = (X, Y)$ and $Z_1 = g_1(W)$ and $Z_2 = g_2(W)$

$$f_{Z_1, Z_2}(z_1, z_2) = P[g_1(W) \leq z_1, g_2(W) \leq z_2]$$

$$f_{Z_1, Z_2}(z_1, z_2) = \iint_{W: g_1(W) \leq z_1, g_2(W) \leq z_2} f_{XY}(x, y) dx dy$$

34 Linear Transformations

$$\begin{bmatrix} V \\ W \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix} = A \begin{bmatrix} X \\ Y \end{bmatrix}$$

Assume A is invertible:

$$\begin{bmatrix} X \\ Y \end{bmatrix} = A^{-1} \begin{bmatrix} V \\ W \end{bmatrix}$$

34.1 Joint PDF of Linear Transformation

Let $Z = g(X, Y)$. The vector Z is:

$$Z = AW \quad Z = \begin{bmatrix} V \\ W \end{bmatrix} \quad W = \begin{bmatrix} X \\ Y \end{bmatrix}$$

The Joint PDF of Z is

$$f_Z(z) = \frac{f_W(A^{-1}z)}{|A|} \quad |A| = \det \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

35 Joint Gaussian RVs

The random variables X, Y are jointly gaussian if:

$$f_{X,Y}(x, y) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho_{XY}^2}} \exp(-\frac{1}{2}(x-\mu_1)^2/\sigma_1^2 + (y-\mu_2)^2/\sigma_2^2 - 2\rho_{XY}(x-\mu_1)(y-\mu_2)/(\sigma_1\sigma_2))$$

43 Common Continuous Random Variables

RV	S	$p_X(k)$	$E[X]$	$\text{VAR}[X]$	$G_X(z)$
Uniform	$[1, 2, \dots, L]$	$\frac{1}{L}$	$\frac{L+1}{2}$	$\frac{L^2-1}{12}$	$\frac{1}{L} \frac{1-z}{1-z_L}$
Bernoulli	$[0, 1]$	$(1-p)p$	p	$p(1-p)$	$\frac{1}{p} \frac{1-pz}{1-p}$
Binomial	$[0, 1, \dots, n]$	$\binom{n}{k} p^k (1-p)^{n-k}$	np	$np(1-p)$	$(q+pz)^n$
-ve Binomial	$[r, r+1, \dots] r \in \mathbb{R}$	$\binom{k-1}{r-1} p^r (1-p)^{k-r}$	$\frac{r}{p}$	$\frac{r(1-p)}{p^2}$	$\left(\frac{p}{1-qz}\right)^r$
Geometric v1	$\{0, 1, 2, \dots\}$	$(1-p)^k p$	$\frac{1-p}{1-p}$	$\frac{p}{1-p}$	$\frac{p}{1-qz}$
Geometric v2	$\{1, 2, \dots\}$	$(1-p)^{k-1} p$	$\frac{1}{p}$	$\frac{p}{p^2}$	$\frac{pz}{1-qz}$
Poisson	$\{0, 1, 2, \dots\}$	$\frac{a^k}{k!} e^{-a}$	a	a	$e^{a(z-1)}$
Zipf	$\{1, 2, \dots, L\}$	$\frac{1}{cL} \frac{1}{k}, c_L = \sum_{j=1}^L \frac{1}{j}$	$\frac{L}{cL}$	$\frac{L(L+1)}{2cL} - \frac{L^2}{c_L^2}$	

$$A = \frac{-1}{2(1-\rho_{XY}^2)} \left[\left(\frac{x-\mu_1}{\sigma_1} \right)^2 - \right]$$

$$2\rho_{XY} \left(\frac{x-\mu_1}{\sigma_1} \right) \left(\frac{y-\mu_2}{\sigma_2} \right) + \left(\frac{y-\mu_2}{\sigma_2} \right)^2 \right]$$

35.1 Joint Standard (Normal) Gaussians

If $X \sim N(0, 1)$, $Y \sim N(0, 1)$, then

$$f_{XY}(x, y) = \frac{1}{2\pi\sqrt{1-\rho^2}} \exp(-\frac{1}{2}(x^2 - 2\rho xy + y^2))$$

$$A = \frac{1}{2(1-\rho^2)} (x^2 - 2\rho_{XY} \cdot xy + y^2)$$

$$f_{XY}(x, y) = g(r) = C \exp\left(-\frac{r^2}{2\sigma^2}\right)$$

35.2 Independence ($m=0, \sigma=1$)

If X, Y independent \leftrightarrow

$$\text{COV}(X, Y) = 0 \quad \rho_{XY}(x, y) = 0$$

$$f_{XY}(x, y) = \frac{1}{2\pi} \exp\left(-\frac{1}{2}(x^2 + y^2)\right)$$

35.3 Independence ($m=0$)

If $X \sim N(0, 1)$, $Y \sim N(0, 1)$, then

$$f_{XY}(x, y) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{1}{2\sigma^2}(x^2 + y^2)\right)$$

35.4 Constant A

If A (exponent of Joint Gaussian) is a constant K

$$K = \left[\left(\frac{x-\mu_1}{\sigma_1} \right)^2 - \dots + \left(\frac{y-\mu_2}{\sigma_2} \right)^2 \right]$$

$$f_{XY}(x, y) = C \exp\left[-\frac{1}{2(1-\rho^2)} K\right] = \text{constant}$$

35.5 Major Axis

If X, Y not independent, then the principal axes has

$$\theta = \frac{1}{2} \arctan^{-1} \tan\left(\frac{2\rho_{XY}\sigma_1\sigma_2}{\sigma_1^2 - \sigma_2^2}\right)$$

35.6 Conditional PDF

The conditional PDF of X given $Y = y$ is

$$f_X(x|y) = \frac{f_{XY}(x, y)}{f_Y(y)} = \frac{1}{2\pi\sigma_1^2\sqrt{1-\rho_{XY}^2}} \exp\left(-\frac{1}{2}\left[\frac{(x-\mu_1)^2}{\sigma_1^2} - \frac{2\rho_{XY}(x-\mu_1)(y-\mu_2)}{\sigma_1\sigma_2} + \frac{(y-\mu_2)^2}{\sigma_2^2}\right]\right)$$

36.1 Mean and Variance of Sum of RVs

$$E[X_1 + X_2 + \dots + X_n] = E[X_1] + E[X_2] + \dots + E[X_n]$$

$$\text{VAR}(X_1 + \dots + X_n) = \sum_{k=1}^n \text{VAR}(X_k)$$

$$+ \sum_{j=1}^n \sum_{k=1, k \neq j} \text{COV}(X_j, X_k), \quad j \neq k$$

If X_1, X_2, \dots, X_n independent, then

$$\text{VAR}(X_1 + \dots + X_n) = \sum_{k=1}^n \text{VAR}(X_k)$$

$$= \sum_{k=1}^n E[X_k^2] - (E[X_k])^2$$

$$= \sum_{k=1}^n \text{Var}(X_k) + \sum_{k=1}^n E[X_k]^2 - (E[X_k])^2$$

$$= \sum_{k=1}^n \text{Var}(X_k)$$

$$= \sum_{k=1}^n \text{Var}(X_k)$$